# Long Nguyen

Master Machine Learning Student University Tübingen

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n2697

fine ln2697.github.io

#### **Education**

2023 - 2025

**University Tübingen** MSc Machine Learning

• Thesis: Addressing the Fundamental Barriers towards End-to-End Driving in Simulation. Advisor: Prof. Dr.-Ing. Andreas Geiger, Kashyap Chitta.

• Overall Grade: 1.1

2020 - 2023

University Tübingen MSc Computer Science (90 ECTS)

• Research Project: Exploring combinatorial optimization and graph visualization. Advisor: Prof. Dr. Michael Kaufmann.

• Overall Grade: 1.1

2017 - 2020

FH Heilbronn BSc Medical Informatics

• Thesis: Automatische Erkennung von Zellformen aus der Blutmikroskopie. Grade 1.0.

• Advisor: Prof. Dr.-Ing. Daniel Pfeifer.

• Overall Grade: 1.8

2011 – 2016 | Wilhelm-Dörpfeld-Gymnasium Abitur (Overall Grade: 1.9)

### **Professional Experience**

2024-2025

**DeepScenario** Software Developer

· Robotics, Machine Learning.

• Data-driven traffic simulation.

2022 - 2024

**Bosch GmBH** Software Developer

• Simulation, Robotics.

• C++ safety simulator for L2 autonomous vehicle system.

2020 - 2024

**University Tübingen** Tutor

Theoretical CS, Algos & Complexity, Statistics, Probability (Bachelor & Master lectures)

• Exercise grading, weekly tutor sessions.

2018 - 2020

FH Heilbronn Tutor

• Database, Software Engineering (Bachelor Lectures).

• Individual group mentoring.

#### Awards

2025	CVPR 2025 - Waymo Vision Based E2E Driving, ranked second
2025	CVPR 2025 - Waymo Scenario Generation, ranked third
2025	Reinforcement Learning Lecture - Hockey Competition, ranked first
2024	Self-Driving Lecture - Modular Pipeline, ranked third
2024	Deep Learning Lecture - Object Detection, ranked fourth
2023	Graph Theory Lecture - Automatic Graph Optimization, ranked first

## **Soft & Technical Skills**

Language Vietnamese (native), German (C2), English (C1)

Programming Python, PyTorch, Numpy, CARLA, Git, OpenCV, CMake, Make, C++

## **Hobbies**

Brazilian jiu-jitsu.

## **Publications**

2026 | 1. Nguyen, L. et al. LEAD: Minimizing Learner-Expert Asymmetry in End-to-End Driving (2026).

2025 | 2. Nguyen, L. et al. Open X-AV: Unifying End-to-End Autonomous Driving Datasets. CVPRW2025 (2025).